Sedimentation

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Introduction

Sedimentation describes the motion of molecules in solutions or particles in suspensions in response to an external force such as gravity, centrifugal force or electric force.

The separation of a dilute slurry or suspension by gravity settling into a clear fluid and s slurry of higher solids content is called sedimentation.



Objective & Application

is to remove the particles from the fluid stream so that the fluid is free of particle contaminants.

Applications of sedimentation: include removal of solids from liquid sewage wastes, settling of crystals from the mother liquor, separation of liquid-liquid mixture from a solvent-extraction stage in settler, water treatment, separation of flocculated particles, lime-soda softening iron and manganese removal, wastewater treatment, solids/sludge/residuals.



Theory for sedimentation

Whenever a particle is moving through a fluid, a number of forces will be acting on the particle.

First, a density difference is needed between the particle and the fluid.

If the densities of the fluid and particle are equal, the buoyant force on the particle will counter balance the external force and the particle will not move relative to the fluid.

There are *three forces* acting on the body:

- Gravity Force
- Buoyant Force
- Drag Force

Mechanics of particle motion in fluids

To describe, two properties need: **1-** *Drag coefficient* **2-***Terminal velocity*

Drag Coefficient

For particle movement in fluids, drag force is a resistance to its motion.

Drag coefficient is a coefficient related to drag force. Overall resistance of fluids act to particle can be described in term of drag force using drag coefficient



Comparing with fluid flow in pipe principle, drag coefficient is similar to friction coefficient or friction factor (f).



For drag coefficient:

$$C_{D} = \frac{(F/A)}{\left(\frac{1}{2}mv^{2}/V\right)}$$
$$F = \frac{1}{2}C_{D}\rho Av^{2}$$

Frictional drag coefficient

1- For flat plate with a laminar boundary layer:

$$C_{D} = \frac{1.328}{N_{R}^{0.5}}$$

2- For flat plate with a turbulent boundary layer:

$$C_{D} = \frac{0.455}{(\log N_{R})^{2.58}}$$

$$N_{R} = \frac{Dv\rho}{\mu}$$

$$D = length of plate = diameter of sphere$$

Frictional drag coefficient:

For *flat plate* with a transition region:

$$C_{D} = \frac{0.455}{(\log N_{R})^{2.58}} - \frac{1700}{N_{R}}$$
$$N_{R} = \frac{Dv\rho}{\mu}$$
$$D = length of plate = diameter of sphere$$

Note: If a plate or circular disk is placed normal to the flow, the total drag will contain negligible frictional drag and does not change with Reynolds number .

Sphere object

At very low Reynolds number (< 0.2), Stoke law is applicable. The inertia forces may be neglected and those of viscosity alone considered.

$$C_D = \frac{24}{N_R}$$

Terminal or Settling Velocity

Settling velocity (v_t) : The terminal velocity at which a particles falls through a fluid.

When a particle is dropped into a column of fluid it immediately accelerates to some velocity and continues falling through the fluid at that velocity (often termed the (*terminal settling velocity*).

The speed of the terminal settling velocity of a particle depends on properties of both the fluid and the particle:

Properties of the particle include:

The size if the particle (*d*).

The density of the material making up the particle (r_p) .

The shape of the particle.

Particle Settling Velocity

Put particle in a still fluid... what happens?

Speed at which particle settles depends on:

Particle properties: *D*, ρ_p , *shape*

Fluid properties: ρ_f , μ , Re



STOKES Settling Velocity

Assumes spherical particle (diameter = d_P) laminar settling F_G depends on the volume and density (ρ_P) of the particle and is given by:

$$F_{G} = \frac{\pi}{6} d_{P}^{3} \times \rho_{P} g = \frac{\pi}{6} \rho_{P} g d_{P}^{3}$$

 F_B is equal to the weight of fluid that is displaced by the particle:

$$F_{B} = \frac{\pi}{6} d_{P}^{3} \times \rho_{f} g = \frac{\pi}{6} \rho_{f} g d_{P}^{3}$$

Where ρ_f is the density of the fluid.

 F_D is known experimentally to vary with the size of the particle, the viscosity of the fluid and the speed at which the particle is traveling through the fluid.

Viscosity is a measure of the fluid's "resistance" to deformation as the particle passes through it.

$$F_{D} = \frac{1}{2} C_{D} \rho_{f} A_{P} v^{2} = 3\pi d_{P} \mu v \qquad \qquad C_{D} = \frac{24}{N_{R}}$$

Where m (the lower case Greek letter mu) is the fluid's dynamic viscosity and v is the velocity of the particle; 3pd is proportional to the area of the particle's surface over which viscous resistance acts.

From basic equation, $\mathbf{F} = mg$ = resultant force:

$$F = ma = m\frac{dv}{dt} = F_G - F_B - F_D$$

With v = terminal velocity or v_t :

$$F_G - F_B - F_D = m\frac{dv}{dt} = 0$$

In the case of $0.0001 < N_R < 0.2$, terminal velocity can be determined by using $C_D = 24/N_R$:

$$v_{t} = \sqrt{\frac{4}{3} \frac{d_{p}(\rho_{p} - \rho_{f})g}{C_{D}\rho_{f}}} = \frac{d_{p}^{2}(\rho_{p} - \rho_{f})g}{18\mu}$$

In the case of $0.2 < N_R < 500$, terminal velocity can be determined by using C_D as:

$$C_D = \frac{24}{N_R} \Big[1 + 0.15 N_R^{0.687} \Big]$$

In the case of $500 < N_R < 200,000$, terminal velocity can be determined by using C_D as:

$$C_D = 0.44$$

	Sphere (any direction ¹)	Thin disk (normal to face ¹)	Thin disk (paraliel to face ¹)	Infinite circular cylinder (normal to axis ¹)
Reynolds No. equ.	d _p Vq _f /η	d, Vesh	2LVes/n	d _p Vq _s /η
Frontal area A,	$(\pi/4) d_p^2$	$(\pi/4 d_p^2)$	$(d_p)L$	$(d_p)L$
Mass mp	$Q_{p}(\pi/6) d_{p}^{3}$	$\varrho_p(\pi/4) d_p^2 L$	$\varrho_p(\pi/4) d_p^2 L$	$\varrho_p(\pi/4) d_p^2 L$
Drag relationships streamline flow $N_R < 0.2$, $F_D =$ $C_D N_R =$ turbulent flow	3πηVd _p 24	8ηVd _p 64/π	(16/3) η <i>Vd_p</i> 64/3	(4π/K) ηVL 8π/K
C_D (average) N_R (range)	0.44 1 × 10 ³ - 2 × 10 ⁵	1.12 >1000	; =	1.2 $1 \times 10^{2} - 2 \times 10^{4}$
Terminal velocity V_t^2	$\frac{4gd_p(\varrho_p-\varrho_f)}{3C\varrho_f}$	$\frac{2gL(\varrho_r-\varrho_f)}{C\varrho_f}$	$\frac{gd_p \pi(\varrho_p - \varrho_f)}{2C\varrho_f}$	$\frac{gd_p \pi(\varrho_p - \varrho_f)}{2C\varrho_f}$

Table 9.1 Comparative summary of equations of motion of spheres, disks and circular cylinders (Adopted from Lapple, 1956)

¹ Direction of flow or motion

L = Thickness of disk, length of rod or cylinder, length of flat plate along direction of flow or motion $K = 2.002 \ln N_B$

 $K = 2.002 \ln N_R$

Laminar (Stokes) vs. Turbulent (Gibbs) settling:



Stoke's Law has several limitations

i) It applies well only to perfect spheres.

The drag force $(3pdmv_t)$ is derived experimentally only for spheres.

Non-spherical particles will experience a different distribution of viscous drag.

ii) It applies only to still water.

Settling through turbulent waters will alter the rate at which a particle settles; upward-directed turbulence will decrease v_t whereas downward-directed turbulence will increase v_t .

iii) It applies to particles **0.1** *mm* or **finer**.

Coarser particles, with larger settling velocities, experience different forms of drag forces.

Stoke's Law overestimates the settling velocity of quartz density particles larger than **0.1** *mm*.



a)When settling velocity is low (d<0.1mm) flow around the particle as it falls smoothly follows the form of the sphere.

Drag forces (\mathbf{F}_{D}) are only due to the *viscosity of the fluid*.

When settling velocity is high (d > 0.1mm) flow separates from the sphere and a wake of eddies develops in its lee.

Pressure forces acting on the sphere vary.





Negative pressure in the lee retards the passage of the particle, adding a new resisting force.

Stoke's Law neglects resistance due to pressure.

iv) Settling velocity is temperature dependant because fluid viscosity and density vary with temperature.

Temp.	μ	ρ	\mathbf{v}_{t}
$^{\circ}\mathrm{C}$	Ns/m ²	Kg/m ³	mm/s
0	1.792 · 10-3	999.9	5
100	2.84 · 10-4	958.4	30



Grain size is sometimes described as a linear dimension based on Stoke's Law:

Stoke's Diameter (d_s) : the diameter of a sphere with a Stoke's settling velocity equal to that of the particle.

$$v_t = \frac{\left(\rho_f - \rho_P\right)g{d_s}^2}{18\mu}$$

Set $d_s = d_P$ and solve for d_P .

$$d_p = \sqrt{\frac{18\mu v_t}{(\rho_f - \rho_P)g}}$$

Settling velocity of dust particles

Example:

Calculate the settling velocity of dust particles of 60 μm diameter in air at 21°C and 100 kPa pressure. Assume that the particles are spherical and density = 1280 kg m⁻³, and that the viscosity of air = 1.8 x 10⁻⁵ N s m⁻² and density of air = 1.2 kg m⁻³.

Solution:

For **60** µm particle:

$$v_{t} = \frac{gD_{p}^{2}(\rho_{p} - \rho)}{18\mu}$$

$$v = \frac{(60 \times 10^{-6})^{2} \times 9.81 \times (1280 - 1.2)}{(18 \times 1.8 \times 10^{-5})}$$

$$= 0.14 \text{ m s}^{-1}$$

Checking the Reynolds number for the $60 \mu m$ particles,

Re =
$$(\nu \rho_b D/\mu)$$

- $= (60 \times 10^{-6} \times 0.14 \times 1.2) / (1.8 \times 10^{-5})$
- = 0.56

HINDERED SETTLING

If the settling is carried out with high concentrations of solids to liquid so that the particles are so close together that collision between the particles is practically continuous and the relative fall of particles involves repeated pushing apart of the lighter by the heavier particles it is called hindered settling.

particles interfere with each other





particle interactions change settling velocity



discrete particles:

higher solids concentration reduces velocity

Flocculating particles:

experiments only



<u>Hindered Settling</u>

 $\varepsilon =$ void fraction

 ψ_p = empirical correlation fraction

$$= \frac{1}{10^{1.82(1-\varepsilon)}}$$

<u>For turbulent flow</u> (Re >10⁴) $v_s = \sqrt{\frac{10*g(\rho_p - \rho_w)d}{3\rho_w}}$

Settling velocity of spherical discrete particle under turbulent flow

Example:

Find the terminal settling velocity of a spherical discrete particle with diameter (0.5 *mm*) and specific gravity of 2.65 settling through water at 20 °C? $\rho_w = 998 \ kg/m^3$, $\mu = 1.002 \times 10^{-3}$

Solution:

$$Sp.gr = \rho_p / \rho_w$$

2.65= $\rho_p / 998$ ------ $\rho_p = 2644.7 \ kg/m^3$ $v_s = \sqrt{\frac{10 * g(\rho_p - \rho_w)d}{3\rho_w}}$
 $v_s = \sqrt{\frac{10 * 9.81(2644.7 - 998) * 0.5 * 10^{-3}}{3 * 998}}$
 $v_s = 0.1642 \ m/sec$

Flocculating Particles (Type II)





Zone Settling & Compression:



$$C_u = \frac{C_o h_o}{h_u}$$

Compression – Compaction:







$$dh/dt = -k(h-h\infty)$$

Zone Settling:



$$V_s = \frac{h_o - h_u}{t_u - t_o} = \frac{h_o - h_i}{t_i}$$

Sedimentation basins (settling tank) :

Sedimentation basins, also called settling tanks or *clarifiers*, are large tanks in which water is made to flow very slowly in order to promote the sedimentation of particles .



The overflow rate (also known as the surface loading or the surface overflow rate) is equal to the settling velocity of the smallest particle which the basin will remove. Surface loading is calculated by dividing the flow by the surface area of the tank. Overflow rate should usually be less than 1,000 gal/day-ft.2 The weir loading is another important factor in sedimentation basin efficiency. Weir loading, Is another factor in sedimentation efficiency weir loading also known as weir overflow rate, is the number of gallons of water passing over a foot of weir per day. The standard weir overflow rate is 10,000 to 14,000 gpd/ft and should be less than 20,000 gpd/ft. Longer weirs allow more water to flow out of the sedimentation basin without exceeding the recommended water velocity.





If a particle settles with vertical speed \boldsymbol{v} , its vertical fall over the length of the tank is

$$h = v \theta = v \frac{L}{u}$$

This length h is either longer than the settling depth H or it is not.

- If $h \ge H$, then the particle hits the bottom before the end of the tank and is collected.
- If h < H, then the particle may or may not hit the bottom, depending on the level at which it starts, If it starts close to the bottom, it will settle on the bottom, but if it starts too high it will wont fail down enough and will escape with the outflow.



1-
$$V = \frac{h.Q}{H.A}$$

It is easy to show that, if h < H, the particles in the lowest h portion of the tank are collected and that those starting within the top H - h portion do not get collected.

This leads us to define a critical settling speed, namely the settling speed of the particles that get barely all collected.

$$h = H$$
 for $v_c = \frac{H}{\theta} = \frac{Hu}{L}$

volumetric h=H in of the terms flowrate

$$v_c = \frac{H}{L}\frac{Q}{WH} = \frac{Q}{WL} = \frac{Q}{A}$$



This critical speed is called the over flow rate

Note: How in this definition, Q is not divided by the cross-sectional area WHbut by the horizontal area of the tank, WL = A

Collecting efficiency:

For particles settling with speed ν faster than ν_c , the collection efficiency is 100%

For particles settling with speed v slower than v_c , the collection efficiency is $\frac{h}{H}$.



And, how does it work in a <u>circular</u> sedimentation tank ?

The radial velocity u varies the radius r. decreasing so that the volumetric flow through the enlarging cross- section remains constant:

$$u=\frac{Q}{2\pi rH}$$

The slope of the settling curve follows the equation

$$\frac{dh}{dr} = \frac{v}{u} = \frac{2\pi r H v}{Q} \implies h = \frac{(\pi R_{outer}^2 - \pi R_{iner}^2) H v}{Q} = \frac{A H v}{Q}$$

The collecting efficiency is

 $\eta = \frac{h}{H} = \frac{Av}{Q} = \frac{v}{(Q/A)} = \frac{v}{v_c}$ same as for the rectangular tank

Typical design values for sedimentation basins

Parameter	Range	Typical values	Units
Rectangular Basin Length Depth width	15 - 90 3 - 5 3 - 24	25 - 40 3.5 6 - 10	m m m
Circular Basin Diameter Depth	4 - 60 3 - 5	12 – 45 4.5	m m
Water Treatment Overflow rate	35 - 110	40 - 80	m/day
Wastewater Treatment Overflow rate	10 - 60	16 - 40	m/day

Η

ν

In time *t*, vertical distance covered is v_t . If $v_t < H$, then fraction (v_t / H) has been collected. If $v_t > H$, then 100% has settled. There is a distribution of particles with various settling velocities. Define: m(v) as the probability distribution. Put another way, m(v) dv = mass fraction of particles with settling speed between *v* and (v + dv).

Detention time :

 $t = \frac{depth}{\frac{tank \, volume}{flow \, rate}}$

Weir length:
$$Lw = \frac{Q_C}{W.loading}$$

Where:

Lw= weir length (ft,m)

Qc =flow in one tank (gal/day, m^3/sec)

في حالة اكثر من خزان = عدد الخزانات/ معدل الجريان

W.L = Weir loading (*gal/day.ft*, *kg/sec.m*)

Depth : the tank depth is calculated as defined:

$$d = \frac{V}{A}$$

Where : d = depth(ft, m) $V = \text{volume}(ft^3, m^3)$ $A = \text{Surface area}(ft^2, m^2)$

For all tank the length has been defines as follows:

$$L = 4W \qquad W = \sqrt{\frac{V}{4d}}$$
$$Qc = \frac{Q}{n}$$

Where :

W = Width of tank ,

Qc= flow in one tank

Q = total flow n = number of tank $A = \frac{Q_c}{O.R}$ A = Surface area Qc = flow rate

O.R= Over flow rate

To calculate tank surface area: A = Qc / O.R.

To calculate tank depth: d = V/A

To calculate width of a rectangular tank where length is four times the width:

$$W = \sqrt{\frac{V}{4d}}$$

<u>Example:</u>

Find dimension of rectangular basin having volume = 3 MLd, t = 4 hr, velocity = 10 cm/min

Solution:

Time = 4x60/1 hour = 240 min

Velocity = 10 cm / min

Length = $240 \min x \ 0.1 = 24 m$

Volume of water at 4 hour = $(3x10^{6}/10^{3})x(4/24) = 500m^{3}$

Cross area= $V/L= 500/24=20.8 \text{ m}^3$

Assume working depth of 3.

Width = 20.8/3 = 7 m

Extra depth 1m of sludge + 0.5 free

Board = 3+1.5 = 4.5 m

Settling tank has size 4.5x24x7

Volume per hour = $3 \times 10^{6} / 24 = 125000 \text{ m}^{3}$

Surface loading (SOR, surface over flow rate):

SOR=(3x106/24)x(1/24x7)

Advantages of circular basin :

1. No dead spaces

2. Low maintenance cost of equipment used for sludge collection and ease of design and construction.

3. The walls of circular tanks act as tension rings, which permit thinner walls than those for rectangular basins. As a result, the circular tanks have a lower capital cost per unit surface area than the rectangular tanks.

(تعمل جدران الخزانات الدائرية كحلقات توتر ، مما يسمح بجدران أرق من تلك الموجودة في الأحواض المستطيلة. نتيجة لذلك ، تتمتع الخزانات الدائرية بتكلفة رأسمالية أقل لكل وحدة مساحة من الخزانات المستطيلة).

Disadvantages of circular basin :

- 1. low hydraulic detention efficiency. (كفاءة احتجاز هيدروليكي منخفضة)
- 2. high risk of short-circuiting. (ارتفاع خطر حدوث قصر في الدائرة الكهربائية)



Sedimentation tank components:

A- Influent Structure (هيكل مؤثر)

purpose:

(1) Dissipate energy of incoming flow by means of baffles. (تبديد طاقة التدفق الوارد عن طريق الحواجز) (2) Distribute the flow equally along the basin width.

(توزيع التدفق بالتساوي على طول عرض الحوض)

(3) Prevent short circuiting by disturbing the thermal or density stratification.

(منع قصر الدائرة عن طريق إزعاج الطبقات الحرارية أو الكثافة)

(4) Promote flocculation. (تعزيز النعتل)

(الحفاظ على فقدان الرأس المنخفض). Keep low head loss (5)

Details of influent structure:

(1) Inlet channel: has a minimum velocity of 0.3m/s to prevent settling of solids.. (قناة المدخل: سرعة لا تقل عن 0.3 متر / ثانية لمنع ترسب المواد الصلبة).

(2) Submerged ports or an overflow weir: Ports have velocities between 4.5 and 9 m/min at design average flow. The spacing between the ports is normally 1–2m with a maximum spacing of 3m.

(المنافذ المغمورة أو السد الفائض تتمتع الموانئ بسرعات تتراوح بين 4.5 و 9 م / دقيقة بمتوسط تدفق التصميم. عادة ما تكون التباعد بين المنافذ 1 - 2 م مع أقصى تباعد 3 م).

(3) A perforated baffle (5% porosity) with ports size between (5-10cm), is typically installed 0.6–0.9m away from the inlet ports and the lower end is about 15–30 cm below the inlet ports. The top of the baffle is kept below the average water surface to allow scum to pass over the top.

(يتم تركيب حاجز مثقوب (5% مسامية) بمنافذ حجمها بين (5-10 سم) ، عادة على بعد 0.6 -0.9 متر من منافذ الدخول ويكون الطرف السفلي حوالي 15-30 سم تحت منافذ الدخول. يتم الاحتفاظ بالجزء العلوي من الحاجز تحت سطح الماء المتوسط للسماح بمرور حثالة فوق القمة).



B-Effluent structure

purposes:

(1) Provide uniform distribution of flow over a large area توفير توزيع منتظم للتدفق على مساحة كبيرة

(2) Minimize lifting of the particles in to the effluent.
قلل من رفع الجسيمات إلى النفايات السائلة
(3) Reduce the escape of floating matter to the effluent.
الحد من تسرب المواد العائمة إلى النفايات السائلة

Details of Effluent structure

1. Overflow weir type : v-notch or straight

2.Baffle in front of an overflow weir: It stops the floating matter from escaping into the effluent (0.6 m submergence minimum)

aping into the enfluent (0.0 in submorgeneration) ---- مقاطع أمام حاجز الفائض: يُمنع المادة العائمة من الهروب إلى النفايات السائلة (0.6 متر غمر كحد أدنى)

3.Effluent launder or channel. (غسيل أو قناة النفايات السائلة) 4.Outlet box. (مندوق تنفيذ)

V-notch is preferred, Why?

•It provide larger head, satisfactory to prevent slime and sludge accumulation إنه يوفر رأسًا أكبر ومرضيًا لمنع تراكم الوحل والحمأة

•The capillary rise can be ignored when V-notch is use.





Bridge drive scraper

Bottom slope of sedimentation tank :

- Rectangular : 1-2%
- Circular: 4-10%

<u>Example:</u>

A sand particle has an average diameter of **1** *mm* and a shape factor of **0.90** and a specific gravity of **2.1**, determine the terminal velocity of the particle settling in water at **20** ^{o}C (kinematic viscosity of water =**1.003**×**10**⁻⁶ *m*²/s and specific gravity =**1**). Drag coefficient can be computed using the following equation:

Solution:

$$\mu_f = 1.003 \times 10^{-6} \times 10^3 = 1.003 \times 10^{-3} \, kg/m.s$$

Settling velocity using Stokes law is:

$$u_t = \frac{g(\rho_P - \rho_f)D_P^2}{18\mu_f} = \frac{9.81 \times (1 \times 10^{-3})^2 \times ((2.1 - 1) \times 1000)}{18 \times 1.003 \times 10^{-3}} = 0.597 \, m/sec$$

$$Re = \emptyset \frac{\rho_f u_t D_P}{\mu_f} = 0.9 \frac{10^3 \times 0.597 \times (1 \times 10^{-3})}{1.003 \times 10^{-3}} = 536.32$$

Since Re > 1, therefore, Newton's law should be used for finding terminal velocity in transition zone. For initial assumption of settling velocity, *stokes law* is used. This initially assumed velocity is used to determine the *Reynolds number* which is further used to fined settling velocity. This iterative procedure is repeated till initial assumed velocity is approximately equal to settling velocity calculated from *Newton's equation*.

Initial drag coefficient is calculated as:

$$C_D = \frac{24}{Re} + \frac{3}{\sqrt{Re}} + 0.34 = 0.5142$$
$$u_t = \sqrt{\frac{4(\rho_P - \rho_f)gD_P}{3\rho_f \phi C_D}} = 0.1763$$

<i>u_t</i> (previous calculated)	Re	C_D	U t	Difference
0.5977	536.3272	0.5143	0.1763	0.4214
0.1763	158.2037	0.7302	0.1480	0.0283
0.148	132.7684	0.7811	0.1431	0.0049
0.1431	128.3690	0.7917	0.1421	0.0010
0.1421	127.5052	0.7939	0.1419	0.0002
0.1419	127.3315	0.7943	0.1419	0.0000

Now, iterative procedure is continued:

Final settling velocity = 0.1419 *m/s*